# Transformations [86 marks]

**1.** [Maximum mark: 16]

EXM.2.AHL.TZ0.16

The matrices A and B are defined by  $A=\begin{pmatrix}3&-2\\2&4\end{pmatrix}$  and  $B=\begin{pmatrix}-1&0\\0&1\end{pmatrix}$  .

(a) Describe fully the geometrical transformation represented by B.

[2]

Markscheme

reflection in the y-axis A1A1

[2 marks]

Triangle X is mapped onto triangle Y by the transformation represented by AB. The coordinates of triangle Y are (0, 0), (-30, -20) and (-16, 32).

(b) Find the coordinates of triangle X.

[5]

Markscheme

$$X = (AB)^{-1}Y$$
 M1

**EITHER** 

$$AB=egin{pmatrix} -3 & -2 \ -2 & 4 \end{pmatrix}$$
 , so  $(AB)^{-1}=egin{pmatrix} -rac{1}{4} & -rac{1}{8} \ -rac{1}{8} & rac{3}{16} \end{pmatrix}$  . MIAS

**OR** 

$$X=B^{-1}A^{-1}Y$$
 M1A1

**THEN** 

$$X=egin{pmatrix} 0 & 10 & 0 \ 0 & 0 & 8 \end{pmatrix}$$
 (A1)

So the coordinates are (0, 0), (10, 0) and (0, 8). **A1** 

<b>[5</b>	m	ar	ks]
L		uı	נכח

(c.i) Find the area of triangle X.

[2]

Markscheme

$$\frac{10\times8}{2}=40\,\mathrm{units^2}$$
 M1A1

[2 marks]

(c.ii) Hence find the area of triangle Y.

[3]

Markscheme

$$\det (AB) = -16$$
 MIAI

Area 
$$=40 imes 16 = 640 \, ext{units}^2$$

[3 marks]

(d) Matrix A represents a combination of transformations:

A stretch, with scale factor 3 and y-axis invariant; Followed by a stretch, with scale factor 4 and x-axis invariant; Followed by a transformation represented by matrix C.

Find matrix C. [4]

Markscheme

A stretch, with scale factor 3 and y-axis invariant is given by  $\begin{pmatrix} 3 & 0 \\ 0 & 1 \end{pmatrix}$ 

A stretch, with scale factor 4 and x-axis invariant is given by  $\begin{pmatrix} 1 & 0 \\ 0 & 4 \end{pmatrix}$ 

So 
$$C=Ainom{3}{0}\ 1igg)^{-1}inom{1}{0}\ 4igg)^{-1}=inom{1}{2}\ \frac{2}{3}\ 1igg)$$
 M1A1

[4 marks]

**2.** [Maximum mark: 12]

EXM.2.AHL.TZ0.15

The matrix A is defined by  $A=egin{pmatrix} 3 & 0 \ 0 & 2 \end{pmatrix}$  .

(a) Describe fully the geometrical transformation represented by A.

[5]

Markscheme

stretch A1

scale factor 3, A1

y-axis invariant (condone parallel to the x-axis) A1

and

stretch, scale factor 2, A7

x-axis invariant (condone parallel to the y-axis) A1

[5 marks]

Pentagon, P, which has an area of 7 cm<sup>2</sup>, is transformed by A.

(b) Find the area of the image of P.

[2]

Markscheme

$$\det\left(A\right) = 6$$
 A1

$$7 \times 6 = 42 \, \mathrm{cm}^2$$
 A1

[2 marks]

The matrix B is defined by 
$$B=rac{1}{2}egin{pmatrix} 3\sqrt{3} & 3 \\ -2 & 2\sqrt{3} \end{pmatrix}$$
 .

B represents the combined effect of the transformation represented by a matrix X, followed by the transformation represented by A.

(c) Find the matrix X.

[3]

Markscheme

$$B = AX$$
 (A1)

$$X = A^{-1}B \quad \text{(M1)}$$

$$X = egin{pmatrix} 0.866 & 0.5 \ -0.5 & 0.866 \end{pmatrix} \left( = egin{pmatrix} rac{\sqrt{3}}{2} & rac{1}{2} \ -rac{1}{2} & rac{\sqrt{3}}{2} \end{pmatrix} 
ight)$$
 A1

[3 marks]

(d) Describe fully the geometrical transformation represented by X.

[2]

Markscheme

Rotation A1

clockwise by 30° about the origin A1

[2 marks]

[4]

The matrices  $m P=egin{pmatrix} 3 & 1 \\ 0 & 1 \end{pmatrix}$  and  $m Q=egin{pmatrix} -4 & 1 \\ 1 & 3 \end{pmatrix}$  represent two transformations.

A triangle T is transformed by  $m{P}$ , and this image is then transformed by  $m{Q}$  to form a new triangle, T1.

(a) Find the single matrix that represents the transformation  $T\prime\!\!\to T$  , which will undo the transformation described above.

Markscheme

# **METHOD 1 (find product of matrices first)**

$$T o T$$
 is represented by  $m{QP}=egin{pmatrix} -4&1\1&3 \end{pmatrix}egin{pmatrix} 3&1\0&2 \end{pmatrix}$  (M1)  $=egin{pmatrix} -12&-2\3&7 \end{pmatrix}$  (A1)

recognizing need to find their  $\left(oldsymbol{Q}oldsymbol{P}
ight)^{-1}$  (M1)

$$(\mathbf{QP})^{-1} = \begin{pmatrix} -12 & -2 \\ 3 & 7 \end{pmatrix}^{-1}$$

$$= \frac{1}{78} \begin{pmatrix} 7 & 2 \\ -3 & -12 \end{pmatrix} \text{ or }$$

$$= \begin{pmatrix} -0.0897435... & -0.0256410... \\ 0.0384615... & 0.153846... \end{pmatrix}$$
 A1

METHOD 2 (find inverses of both matrices first)

recognizing need to find inverse of both  $m{P}$  and  $m{Q}$  (M1)

$$m{P}^{-1} = egin{pmatrix} rac{1}{3} & -rac{1}{6} \ 0 & rac{1}{2} \end{pmatrix}$$
 and  $m{Q}^{-1} = egin{pmatrix} -rac{3}{13} & rac{1}{13} \ rac{1}{13} & rac{4}{13} \end{pmatrix}$  (A1)

$$T$$
 /  $T$  is represented by  $m{P}^{-1}m{Q}^{-1}=egin{pmatrix} 3 & 1 \ 0 & 2 \end{pmatrix}^{-1}egin{pmatrix} -4 & 1 \ 1 & 3 \end{pmatrix}^{-1}$  (M1)

$$=rac{1}{78}inom{7}{-3} -12$$
 or  $=inom{-0.0897435\dots -0.0256410\dots}{0.0384615\dots 0.153846\dots}$  At

**Note:** In METHOD 1, award *M1A0M1A0* if they multiply the matrices in the wrong order.

In METHOD 2, award *M1A1M1A0* if they multiply the matrices in the wrong order.

[4 marks]

The area of  $T\prime$  is  $273~{\rm cm}^2$ .

(b) Using your answer to part (a), or otherwise, determine the area of  ${\cal T}$ .

[3]

Markscheme

$$egin{pmatrix} \det\left[-rac{1}{78}inom{7}{-3} & 2 \ -3 & -12 \end{pmatrix}
ight]=igg)-rac{1}{78} ext{ or } \ \left(\detinom{-12}{3} & 7 
ight)=igg)-78 ag{A1}$$

area of 
$$T\prime=|\det {m QP}| imes {
m area}$$
 of  $T$  **OR** area of  $T=\left|\det {({m QP})}^{-1}\right| imes {
m area}$  of  $T\prime$  (M1)  $\Rightarrow$  area of  $T=273 imes rac{1}{78}$   $=3.5~{
m (cm}^2)$ 

**Note:** Award *(A1)(M0)A0* for an answer of  $-3.5~({\rm cm}^2)$  with or without working. Accept an answer of  $4.04~({\rm cm}^2)$  from use of 3sf values in their answer to part (a).

[3 marks]

**4.** [Maximum mark: 8]

The transformation T is represented by the matrix  $m{M}=egin{pmatrix} 2 & -4 \ 3 & 1 \end{pmatrix}$  .

A pentagon with an area of  $12\,\mathrm{cm}^2$  is transformed by T.

(a) Find the area of the image of the pentagon.

[2]

# Markscheme

attempt to find  $\det\left( oldsymbol{M} 
ight)$ 

(M1)

= 14

$$(12 \times 14) = 168 \, \mathrm{cm}^2$$

A1

[2 marks]

Under the transformation T , the image of point  ${
m X}$  has coordinates  $(2t-3,\ 6-5t)$  , where  $t\in \mathbb{R}$  .

(b) Find, in terms of t, the coordinates of X.

[6]

Markscheme

let X have coordinates (x, y)

**METHOD 1** 

$$oldsymbol{M} egin{pmatrix} x \ y \end{pmatrix} = egin{pmatrix} 2t-3 \ 6-5t \end{pmatrix}$$
 (M1)

$$egin{pmatrix} x \ y \end{pmatrix} = oldsymbol{M}^{-1} egin{pmatrix} 2t-3 \ 6-5t \end{pmatrix}$$
 (A1)

$$oldsymbol{M}^{-1}=rac{1}{14}inom{1}{-3} rac{4}{2}$$

$$egin{pmatrix} x \ y \end{pmatrix} = rac{1}{14} egin{pmatrix} 2t - 3 + 24 - 20t \ -6t + 9 + 12 - 10t \end{pmatrix}$$
 (M1)

$$egin{pmatrix} x \ y \end{pmatrix} = rac{1}{14} egin{pmatrix} 21 - 18t \ 21 - 16t \end{pmatrix}$$
 or  $ig(rac{21 - 18t}{14}, rac{21 - 16t}{14}ig)$ 

# **METHOD 2**

writing two simultaneous equations (M1)

$$2x - 4y = 2t - 3 \tag{A1}$$

$$3x + y = 6 - 5t \tag{A1}$$

attempting to solve the equations (M1)

$$(x, y) = \left(\frac{3}{2} - \frac{9t}{7}, \frac{3}{2} - \frac{8t}{7}\right)$$
 A1A1

[6 marks]

**5.** [Maximum mark: 18]

A transformation, T, of a plane is represented by r'=Pr+q, where P is a  $2\times 2$  matrix, q is a  $2\times 1$  vector, r is the position vector of a point in the plane and r' the position vector of its image under T.

The triangle OAB has coordinates  $(0,\ 0)$ ,  $(0,\ 1)$  and  $(1,\ 0)$ . Under T, these points are transformed to  $(0,\ 1)$ ,  $\left(\frac{1}{4},\ 1+\frac{\sqrt{3}}{4}\right)$  and  $\left(\frac{\sqrt{3}}{4},\ \frac{3}{4}\right)$  respectively.

(a.i) By considering the image of  $(0,\ 0)$  , find  $oldsymbol{q}$ .

[2]

Markscheme

$$oldsymbol{P}igg(egin{matrix} 0 \ 0 \end{pmatrix} + oldsymbol{q} = igg(egin{matrix} 0 \ 1 \end{pmatrix}$$
 (M1)

$$oldsymbol{q} = egin{pmatrix} 0 \ 1 \end{pmatrix}$$
 at

[2 marks]

(a.ii) By considering the image of  $(1,\ 0)$  and  $(0,\ 1)$ , show that

$$m{P}=egin{pmatrix} rac{\sqrt{3}}{4} & rac{1}{4} \ -rac{1}{4} & rac{\sqrt{3}}{4} \end{pmatrix}.$$

[4]

Markscheme

**EITHER** 

$$m{P}inom{1}{0}+inom{0}{1}=inom{rac{\sqrt{3}}{4}}{rac{3}{4}}$$
 M

hence 
$$m{P}inom{1}{0}=egin{pmatrix} rac{\sqrt{3}}{4} \ -rac{1}{4} \end{pmatrix}$$
 . A1

$$m{P}inom{0}{1}+inom{0}{1}=inom{rac{1}{4}}{1+rac{\sqrt{3}}{4}}$$
 M1

hence 
$$m{P}inom{0}{1}=inom{rac{1}{4}}{rac{\sqrt{3}}{4}}$$
 A1

**OR** 

$$egin{pmatrix} a & b \ c & d \end{pmatrix} egin{pmatrix} 1 \ 0 \end{pmatrix} + egin{pmatrix} 0 \ 1 \end{pmatrix} = egin{pmatrix} rac{\sqrt{3}}{4} \ rac{3}{4} \end{pmatrix}$$
 M1

hence 
$$\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{3}}{4} \\ -\frac{1}{4} \end{pmatrix}$$

$$\begin{pmatrix} a \\ c \end{pmatrix} = \begin{pmatrix} \frac{\sqrt{3}}{4} \\ -\frac{1}{4} \end{pmatrix}$$

$$egin{pmatrix} a & b \ c & d \end{pmatrix} egin{pmatrix} 0 \ 1 \end{pmatrix} + egin{pmatrix} 0 \ 1 \end{pmatrix} = egin{pmatrix} rac{1}{4} \ 1 + rac{\sqrt{3}}{4} \end{pmatrix}$$
 Mix

$$egin{pmatrix} a & b \ c & d \end{pmatrix} egin{pmatrix} 0 \ 1 \end{pmatrix} = egin{pmatrix} rac{1}{4} \ rac{\sqrt{3}}{4} \end{pmatrix}$$
 A1

$$\binom{b}{d} = \binom{\frac{1}{4}}{\frac{\sqrt{3}}{4}}$$

THEN

$$\Rightarrow m{P} = egin{pmatrix} rac{\sqrt{3}}{4} & rac{1}{4} \ -rac{1}{4} & rac{\sqrt{3}}{4} \end{pmatrix}$$
 AG

[4 marks]

 $oldsymbol{P}$  can be written as  $oldsymbol{P} = oldsymbol{R} oldsymbol{S}$ , where  $oldsymbol{S}$  and  $oldsymbol{R}$  are matrices.

 $m{S}$  represents an enlargement with scale factor 0.5, centre  $(0,\ 0)$ .

 $m{R}$  represents a rotation about  $(0,\ 0)$ .

(b) Write down the matrix S.

[1]

Markscheme

$$\begin{pmatrix} \frac{1}{2} & 0 \\ 0 & \frac{1}{2} \end{pmatrix} \qquad \textbf{A7}$$

[1 mark]

(c.i) Use  $oldsymbol{P} = oldsymbol{R} oldsymbol{S}$  to find the matrix  $oldsymbol{R}$ .

[4]

Markscheme

**EITHER** 

$$oldsymbol{S}^{-1}=egin{pmatrix} 2 & 0 \ 0 & 2 \end{pmatrix}$$
 (A1)

$$oldsymbol{R} = oldsymbol{P} oldsymbol{S}^{-1}$$
 (M1)

**Note:** The *M1* is for an attempt at rearranging the matrix equation. Award even if the order of the product is reversed.

$$m{R}=egin{pmatrix} rac{\sqrt{3}}{4} & rac{1}{4} \ -rac{1}{4} & rac{\sqrt{3}}{4} \end{pmatrix} egin{pmatrix} 2 & 0 \ 0 & 2 \end{pmatrix}$$
 (A1)

**OR** 

$$\begin{pmatrix} \frac{\sqrt{3}}{4} & \frac{1}{4} \\ -\frac{1}{4} & \frac{\sqrt{3}}{4} \end{pmatrix} = \boldsymbol{R} \begin{pmatrix} 0.5 & 0 \\ 0 & 0.5 \end{pmatrix}$$

let 
$$oldsymbol{R} = egin{pmatrix} a & b \ c & d \end{pmatrix}$$

attempt to solve a system of equations M1

$$rac{\sqrt{3}}{4}=0.5a, \quad rac{1}{4}=0.5b$$
  $-rac{1}{4}=0.5c, \quad rac{\sqrt{3}}{4}=0.5d$  A2

Note: Award A1 for two correct equations, A2 for all four equations correct.

**THEN** 

$$m{R} = egin{pmatrix} rac{\sqrt{3}}{2} & rac{1}{2} \ -rac{1}{2} & rac{\sqrt{3}}{2} \end{pmatrix}$$
 or  $egin{pmatrix} 0.866 & 0.5 \ -0.5 & 0.866 \end{pmatrix}$  or  $egin{pmatrix} 0.866025 \dots & 0.5 \ -0.5 & 0.866025 \dots \end{pmatrix}$ 

**Note:** The correct answer can be obtained from reversing the matrices, so do not award if incorrect product seen. If the given answer is obtained from the product  $m{R}=m{S}^{-1}m{P}$ , award (A1)(M1)(A0)A0.

[4 marks]

(c.ii) Hence find the angle and direction of the rotation represented by  $m{R}$ .

[3]

Markscheme

clockwise A1

arccosine or arcsine of value in matrix seen (M1)

 $30^{\circ}$  A1

**Note:** Both *A1* marks are dependent on the answer to part (c)(i) and should only be awarded for a valid rotation matrix.

[3 marks]

The transformation T can also be described by an enlargement scale factor  $\frac{1}{2}$ , centre  $(a,\ b)$ , followed by a rotation about the same centre  $(a,\ b)$ .

(d.i) Write down an equation satisfied by  $\binom{a}{b}$ . [1]

Markscheme

#### **METHOD 1**

$$egin{pmatrix} a \ b \end{pmatrix} = oldsymbol{P}igg(egin{pmatrix} a \ b \end{pmatrix} + oldsymbol{q}$$
 at

#### **METHOD 2**

$$egin{pmatrix} x' \ y' \end{pmatrix} = oldsymbol{P}igg(egin{matrix} x-a \ y-b \end{pmatrix} + igg(egin{matrix} a \ b \end{pmatrix}$$
 A1

**Note**: Accept substitution of x and y (and  $x\prime$  and  $y\prime$ ) with particular points given in the question.

[1 mark]

(d.ii) Find the value of a and the value of b.

Markscheme

#### **METHOD 1**

solving 
$$egin{pmatrix} a \\ b \end{pmatrix} = m{P} egin{pmatrix} a \\ b \end{pmatrix} + m{q}$$
 using simultaneous equations or  $m{a} = (m{I} - m{P})^{-1} m{q}$  (M1)  $a = 0.651 \ (0.651084\ldots), \ b = 1.48 \ (1.47662\ldots)$  A1A1  $\left(a = \frac{5+2\sqrt{3}}{13}, \ b = \frac{14+3\sqrt{3}}{13} \right)$ 

#### **METHOD 2**

[3]

$$egin{pmatrix} 0 \ 1 \end{pmatrix} = oldsymbol{P}igg(egin{pmatrix} 0-a \ 0-b \end{pmatrix} + igg(egin{pmatrix} a \ b \end{pmatrix} \qquad ext{(M1)}$$

**Note:** This line, with any of the points substituted, may be seen in part (d)(i) and if so the *M1* can be awarded there.

$$egin{pmatrix} 0 \ 1 \end{pmatrix} = (m{I} - m{P}) egin{pmatrix} a \ b \end{pmatrix}$$
  $a = 0.651084\ldots, \ b = 1.47662\ldots$  A1A1  $\Big(a = rac{5 + 2\sqrt{3}}{13}, \ b = rac{14 + 3\sqrt{3}}{13} \Big)$ 

[3 marks]

A flying drone is programmed to complete a series of movements in a horizontal plane relative to an origin O and a set of x-y-axes.

In each case, the drone moves to a new position represented by the following transformations:

- a rotation anticlockwise of  $\frac{\pi}{6}$  radians about O a reflection in the line  $y=\frac{x}{\sqrt{3}}$
- a rotation clockwise of  $\frac{\pi}{3}$  radians about O.

All the movements are performed in the listed order.

Write down each of the transformations in matrix form, clearly (a.i) stating which matrix represents each transformation.

[6]

# Markscheme

**Note:** For clarity, exact answers are used throughout this markscheme. However it is perfectly acceptable for candidates to write decimal values (e.g.  $\frac{\sqrt{3}}{2} = 0.866$ ).

rotation anticlockwise 
$$\frac{\pi}{6}$$
 is  $\begin{pmatrix} 0.866 & -0.5 \\ 0.5 & 0.866 \end{pmatrix}$  OR  $\begin{pmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{pmatrix}$ 

reflection in 
$$y=\frac{x}{\sqrt{3}}$$

(M1)A1

$$\tan \theta = \frac{1}{\sqrt{3}}$$
 (M1)

$$\Rightarrow 2 heta = rac{\pi}{3}$$
 (A1)

matrix is 
$$\begin{pmatrix} 0.5 & 0.866 \\ 0.866 & -0.5 \end{pmatrix}$$
 OR  $\begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & -\frac{1}{2} \end{pmatrix}$ 

rotation clockwise 
$$\frac{\pi}{3}$$
 is  $\begin{pmatrix} 0.5 & 0.866 \\ -0.866 & 0.5 \end{pmatrix}$  **OR**  $\begin{pmatrix} \frac{1}{2} & \frac{\sqrt{3}}{2} \\ -\frac{\sqrt{3}}{2} & \frac{1}{2} \end{pmatrix}$ 

[6 marks]

(a.ii) Find a single matrix  ${m P}$  that defines a transformation that represents the overall change in position.

Markscheme

**Note:** For clarity, exact answers are used throughout this markscheme. However it is perfectly acceptable for candidates to write decimal values  $\left(e.g.\ \frac{\sqrt{3}}{2}=0.\,866\right)$ .

an attempt to multiply three matrices (M1)

$$m{P} = egin{pmatrix} rac{1}{2} & rac{\sqrt{3}}{2} \\ -rac{\sqrt{3}}{2} & rac{1}{2} \end{pmatrix} egin{pmatrix} rac{1}{2} & rac{\sqrt{3}}{2} \\ rac{\sqrt{3}}{2} & -rac{1}{2} \end{pmatrix} egin{pmatrix} rac{\sqrt{3}}{2} & -rac{1}{2} \\ rac{1}{2} & rac{\sqrt{3}}{2} \end{pmatrix} \qquad ext{(A1)}$$

$$m{P} = egin{pmatrix} rac{\sqrt{3}}{2} & -rac{1}{2} \ -rac{1}{2} & -rac{\sqrt{3}}{2} \end{pmatrix}$$
 or  $egin{pmatrix} 0.866 & -0.5 \ -0.5 & -0.866 \end{pmatrix}$  at

[3]

(a.iii) Find  $m{P}^2$ .

# Markscheme

**Note:** For clarity, exact answers are used throughout this markscheme. However it is perfectly acceptable for candidates to write decimal values  $\left(e.g.\ \frac{\sqrt{3}}{2}=0.\ 866\right)$ .

$$egin{pmatrix} m{P}^2 = egin{pmatrix} rac{\sqrt{3}}{2} & -rac{1}{2} \ -rac{1}{2} & -rac{\sqrt{3}}{2} \end{pmatrix} egin{pmatrix} rac{\sqrt{3}}{2} & -rac{1}{2} \ -rac{1}{2} & -rac{\sqrt{3}}{2} \end{pmatrix} = egin{pmatrix} 1 & 0 \ 0 & 1 \end{pmatrix}$$

**Note:** Do not award **A1** if final answer not resolved into the identity matrix I

[2]

[1 mark]

(a.iv) Hence state what the value of  ${m P}^2$  indicates for the possible movement of the drone.

Markscheme

**Note:** For clarity, exact answers are used throughout this markscheme. However it is perfectly acceptable for candidates to write decimal values  $\left(e.g.\ \frac{\sqrt{3}}{2}=0.866\right)$ .

if the overall movement of the drone is repeated

A1

the drone would return to its original position

A1

[2 marks]

(b) Three drones are initially positioned at the points A,B and C. After performing the movements listed above, the drones are positioned at points  $A\prime$ ,  $B\prime$  and  $C\prime$  respectively.

Show that the area of triangle ABC is equal to the area of triangle  $A\prime B\prime C\prime$  .

[2]

Markscheme

**Note:** For clarity, exact answers are used throughout this markscheme. However it is perfectly acceptable for candidates to write decimal values  $\left(e.g.\ \frac{\sqrt{3}}{2}=0.866\right)$ .

#### **METHOD 1**

 $|\det m{P}|=\left|\left(-rac{3}{4}
ight)-\left(rac{1}{4}
ight)
ight|=1$  and area of triangle ABC= area of triangle A/B/C/  $imes |\det m{P}|$  R1 area of triangle ABC= area of triangle A/B/C/ AG

**Note:** Award at most *A1R0* for responses that omit modulus sign.

# **METHOD 2**

statement of fact that rotation leaves area unchanged R1

statement of fact that reflection leaves area unchanged  $$\it R1$$  area of triangle ABC= area of triangle  $A\prime B\prime C\prime$ 

[2 marks]

(c) Find a single transformation that is equivalent to the three transformations represented by matrix P.

[4]

# Markscheme

**Note:** For clarity, exact answers are used throughout this markscheme. However it is perfectly acceptable for candidates to write decimal values  $\left(e.g.\ \frac{\sqrt{3}}{2}=0.\,866\right)$ .

attempt to find angles associated with values of elements in matrix  $m{P}$  (M1)

$$\begin{pmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ -\frac{1}{2} & -\frac{\sqrt{3}}{2} \end{pmatrix} = \begin{pmatrix} \cos\left(-\frac{\pi}{6}\right) & \sin\left(-\frac{\pi}{6}\right) \\ \sin\left(-\frac{\pi}{6}\right) & -\cos\left(-\frac{\pi}{6}\right) \end{pmatrix}$$

reflection (in  $y = (\tan \theta)x$ ) (M1)

where  $2 heta=-rac{\pi}{6}$   $\hspace{0.2in}$  A1

reflection in  $y= an\!\left(-rac{\pi}{12}
ight)\!x \ \ (=-0.\,268x)$ 

[4 marks]

[2]

[3]

A geometric transformation  $T: \begin{pmatrix} x \\ y \end{pmatrix} \mapsto \begin{pmatrix} x\prime \\ y\prime \end{pmatrix}$  is defined by

$$T: egin{pmatrix} x\prime \\ y\prime \end{pmatrix} = egin{pmatrix} 7 & -10 \\ 2 & -3 \end{pmatrix} egin{pmatrix} x \\ y \end{pmatrix} + egin{pmatrix} -5 \\ 4 \end{pmatrix}.$$

(a) Find the coordinates of the image of the point  $(6,\;-2)$ .

Markscheme

$$egin{pmatrix} 7&-10\ 2&-3 \end{pmatrix} egin{pmatrix} 6\ -2 \end{pmatrix} + egin{pmatrix} -5\ 4 \end{pmatrix}$$
 (M1)  $=egin{pmatrix} 57\ 22 \end{pmatrix}$  or  $(57,\ 22)$  at

[2 marks]

(b) Given that  $T: \binom{p}{q} \mapsto 2 \binom{p}{q}$  , find the value of p and the value of q.

Markscheme

$$egin{pmatrix} 2p \ 2q \end{pmatrix} = egin{pmatrix} 7 & -10 \ 2 & -3 \end{pmatrix} egin{pmatrix} p \ q \end{pmatrix} + egin{pmatrix} -5 \ 4 \end{pmatrix}$$
 (M1)

$$7p - 10q - 5 = 2p$$

$$2p - 3q + 4 = 2q$$
 (A1)

solve simultaneously:

$$p = 13, q = 6$$
 A1

Note: Award  $\emph{A0}$  if 13 and 6 are not labelled or are labelled the other way around.

[3 marks]

(c) A triangle L with vertices lying on the xy plane is transformed by T.

Explain why both  ${\cal L}$  and its image will have exactly the same area.

[2]

Markscheme

$$\det \begin{pmatrix} 7 & -10 \\ 2 & -3 \end{pmatrix} = -1 \left( \mathbf{OR} \left| \det \begin{pmatrix} 7 & -10 \\ 2 & -3 \end{pmatrix} \right| = 1 \right)$$

scale factor of image area is therefore (|-1|=)1 (and the translation does not affect the area)  $\it A1$ 

[2 marks]

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